

PONSSE EPEC FORWARD'27 ECOSYSTEM WEBINAR

21.2.2025



FORWARD'27 ECOSYSTEM WEBINAR

Quidelines

- Kindly keep your microphones muted
- The webinar will be recorded
- Q&A will be at the end

- Welcome to Ponsse Epec FORWARD'27 webinar!

FORWARD'27 ECOSYSTEM WEBINAR

13:00 Welcome and webinar guidelines, Agenda

Co-Innovation -projects:

13:05 **FOSSA II:** *Jukka Kömi*, Professor, University of Oulu
Commentator: *Kalle Einola*, Director, Research & Programs, Ponsse R&D

13:20 **TwinFlow:** *Jari Juhanko*, Staff Scientist, Aalto University
Commentator: *Jari Roivainen*, Process Owner, Measurements and New Products,
Ponsse Operations

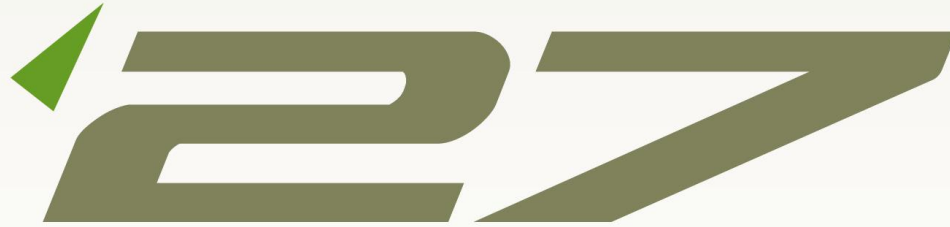
13:35 **Aurora:** *Jukka Yrjänäinen*, Project Manager, Tampere University
Commentator: *Mikko Haapalainen*, Director, Control Systems, Ponsse R&D
/ Kalle Einola

13:50 Q&A

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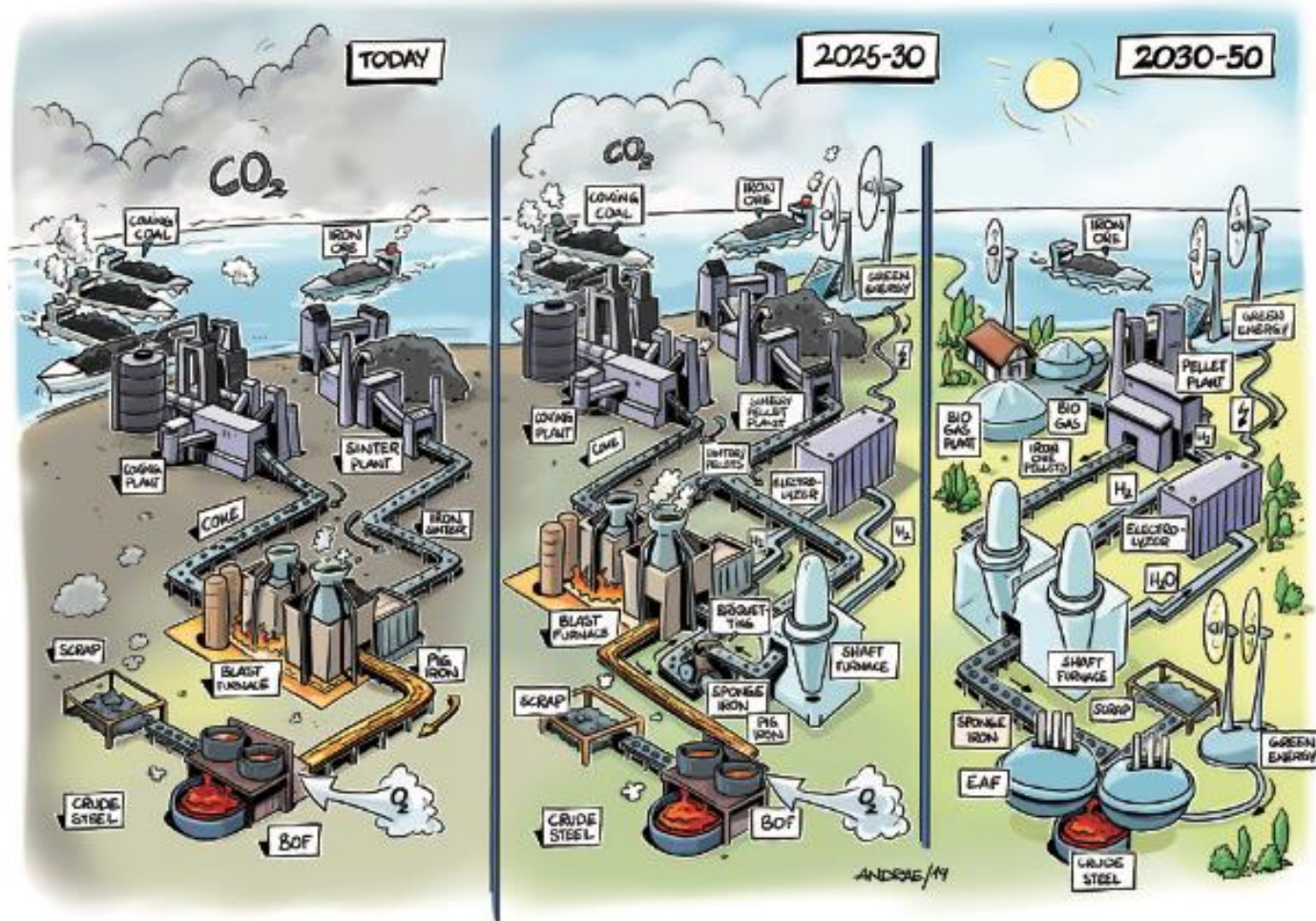
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**PONSSE EPEC FORWARD'27
EKOSYSTEEMIWEBINAARI**

FOSSAII



Future Steelmaking, Steels and Steel Applications



Finnish metals (steel) industry is committed to reduce greenhouse gas emissions by 70 % from the level of 2008.

In addition, it is estimated that the use of **ultrahigh-strength steels** in vehicles will decrease greenhouse gas emissions by at least the same amount.

So, even 15 % reduction in Finland's CO_2 emissions is possible, with enormous potential on a global scale.



Lähtökohta: Fossiivapaa terästuonto

Traditional versus HYBRIT technology

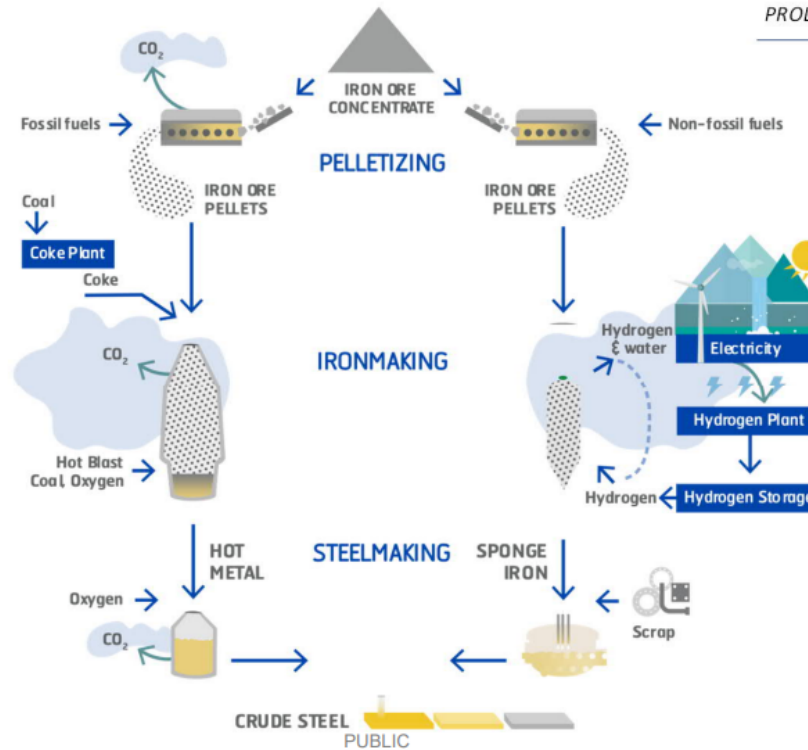


BLAST FURNACE

HYBRIT – a joint venture with Vattenfall and LKAB

PRODUCTION INTENSITY PER TONNE OF CRUDE STEEL

| Global average | SSAB |
|--------------------------|--------------------------|
| 2,000 kg CO ₂ | 1,600 kg CO ₂ |
| | 81 kWh Oil |
| | 5,510 kWh Coal |
| | 235 kWh Electricity |



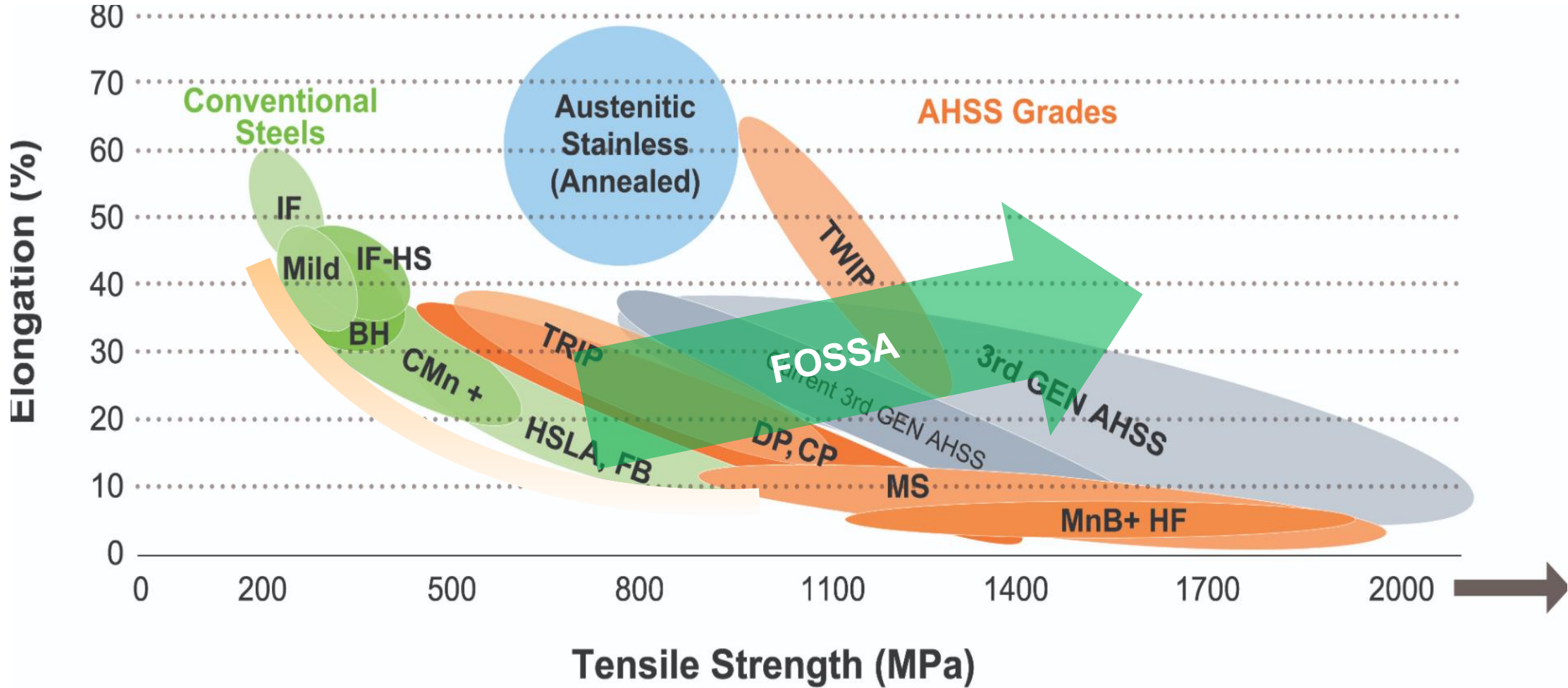
PRODUCTION INTENSITY PER TONNE OF CRUDE STEEL

| HYBRIT |
|-----------------------|
| 25 kg CO ₂ |
| 42 kWh Graphite |
| 560 kWh Bio |
| 3,488 kWh Electricity |





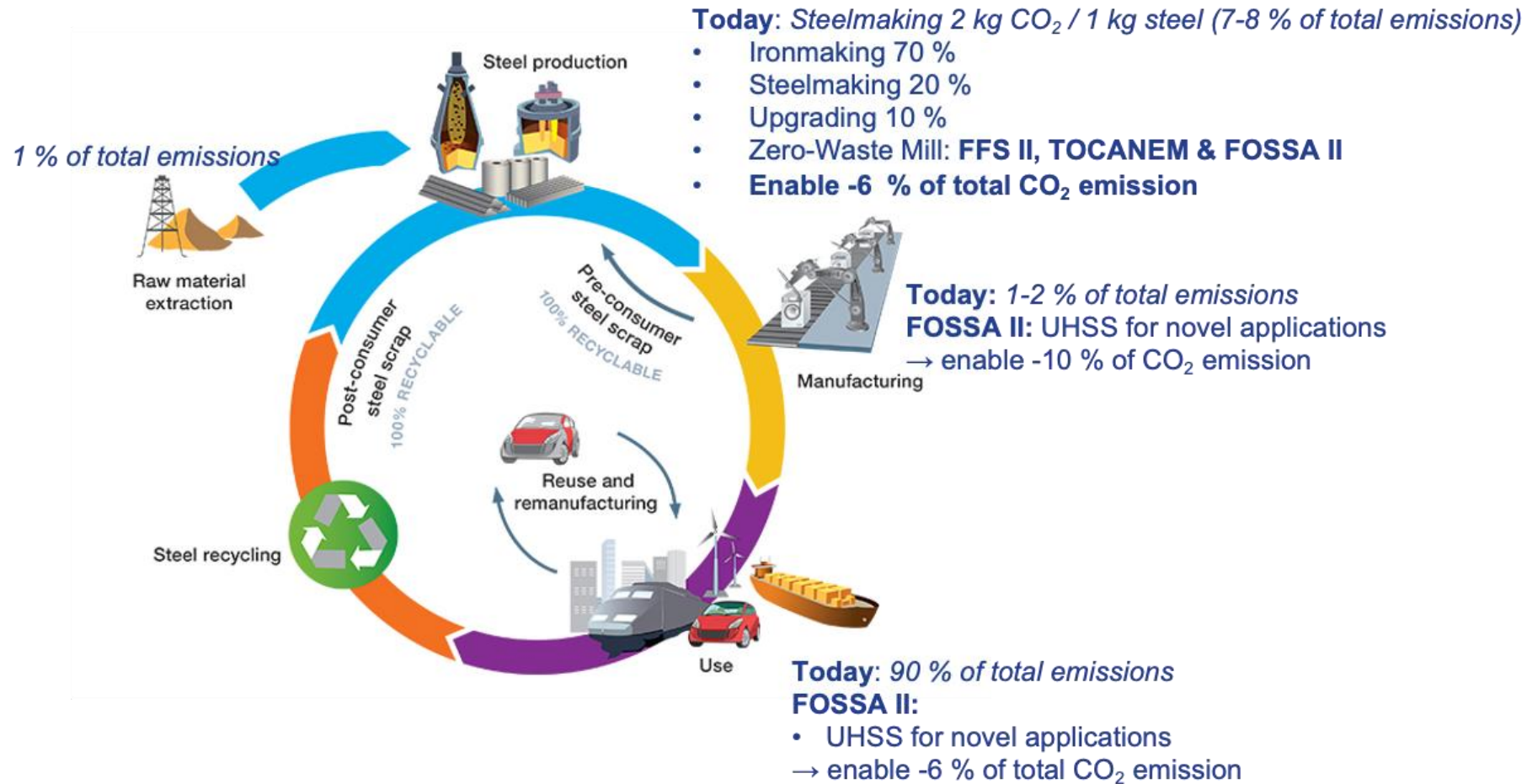
Teräskehitys UHSS/AHSS teräslajit





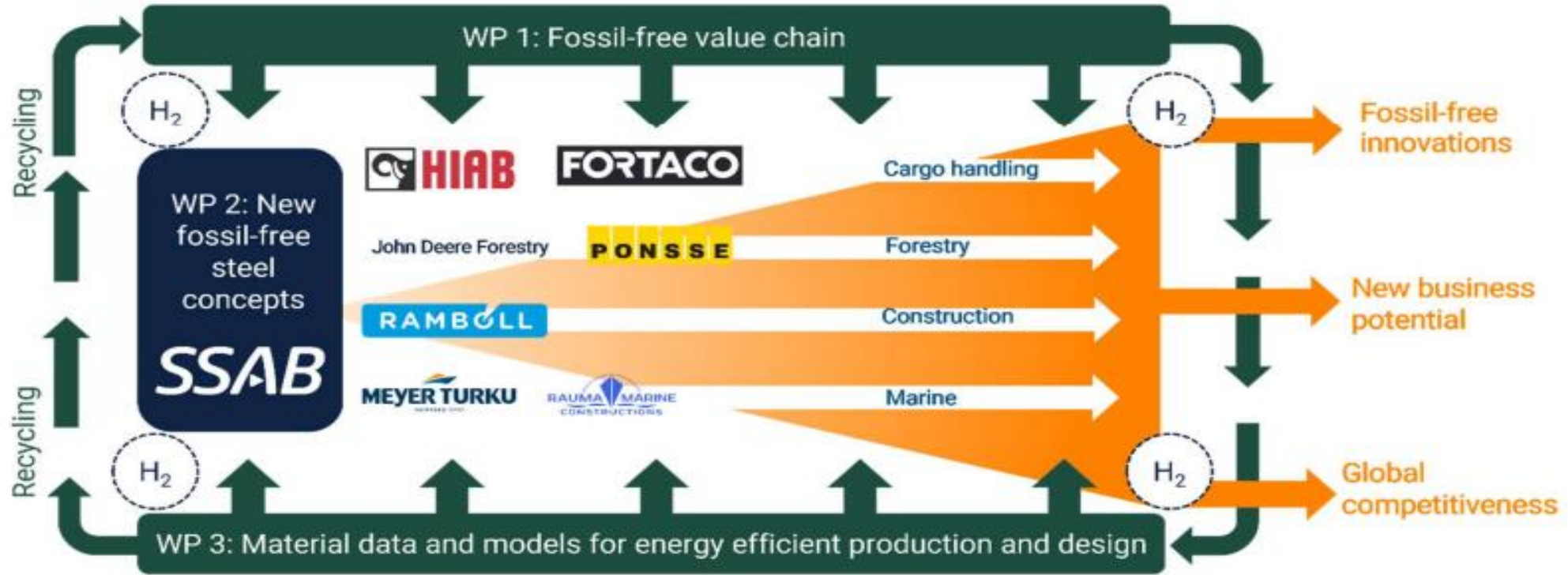
FOSSA, FFS & TOCANEM – Impact and focus areas

Steels' life cycle – affects even 60% of world's GDP

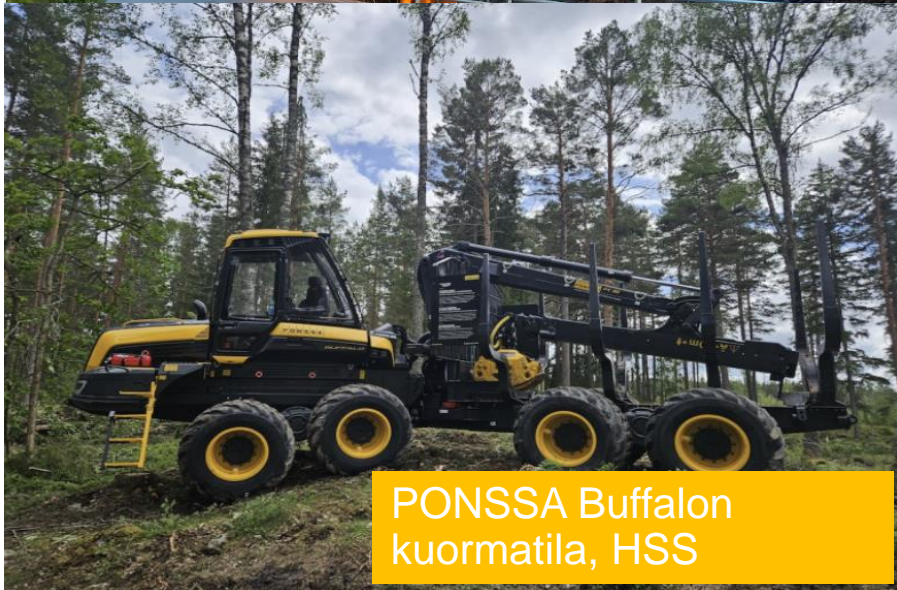




FOSSA konsortio



FOSSA some results



SSAB Zero™

A fossil carbon emission-free steel based on recycled steel, produced using fossil-free electricity and biogas. The first commercial steel of its kind – launched in 2023.

0.0 kg CO₂e emissions per kg steel

The fossil carbon emissions in operations including purchased energy (scope 1-2 and transportation between SSAB sites)

Figure 2: SSAB Zero 0.0kg CO₂ emission per kg steel (a)

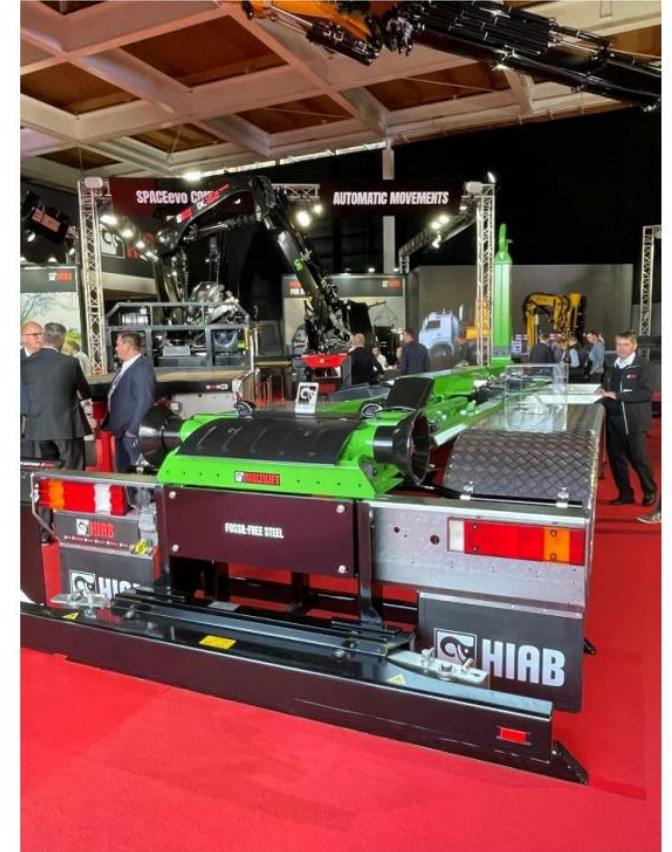


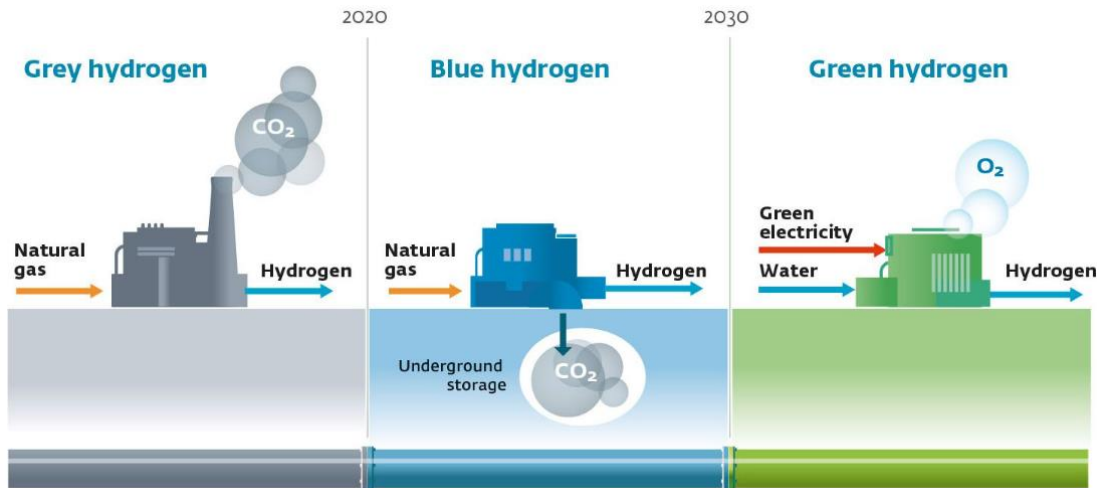
Figure 3: Multilift Ultima 18S FFS in IAA exhibition



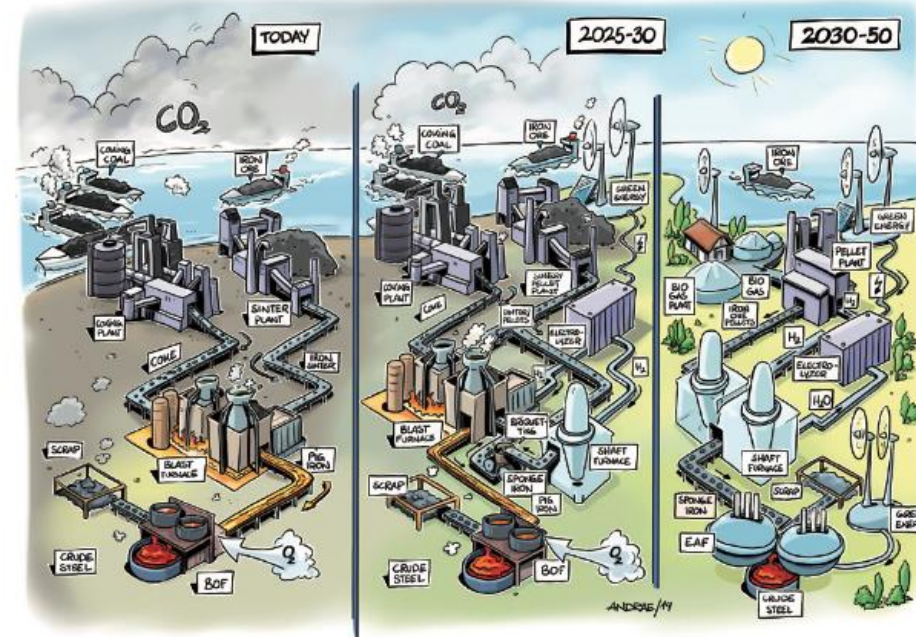
From Sustainable Thinking to Fossil-free Business

*“The world we have created is a product of our thinking. If we want to change the world, we must change our thinking”,
Albert Einstein*

Energy industry (investment programs ongoing)
→ *increases the price of energy*



Steel industry (investment programs ongoing)



EU's carbon goal will cost steelmaker up to €40bn (with 136 Mtn steel production)

→ *increases the production costs*



Manufacturing → *increases the price of production*

Use and reuse → *increases the costs*

100 % recycling → *increases the costs*

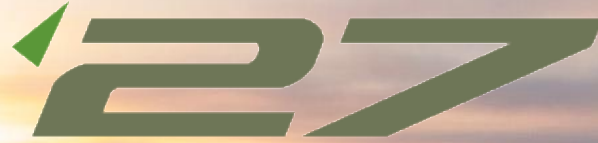
So, this will become a profitable business, and we are part of it



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Thank you!

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Merging Information Technologies (IT) and Operational Technologies (OT) for enhanced production-intralogistics

Ponsse Epec FORWARD'27
ekosysteemiwebinaari 21.2.2025

Jari Juhanko, D.Sc, Project Coordinator
Aalto University



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Facts & Figures

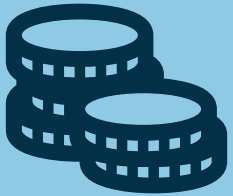
- 3 years (2024-2026)
- 10 companies
- 2 universities, 9 research teams
- Budget 9,3 M€ (universities 3,9 M€)
- Funded by BF Data Economy Program

Part of Konecranes' and Ponsse's Veturi programs



Data driven operations

Business case



Legal framework



Enabling technology

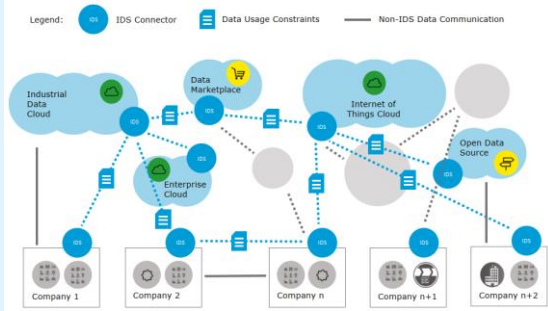


People (Social sustainability)



European IDS Reference Architecture Model

- Data ecosystem – data space with specific partner roles
- Common standards and rules for data sharing
- Data sovereignty
- Governance model and rulebook
- Enables added value for partners

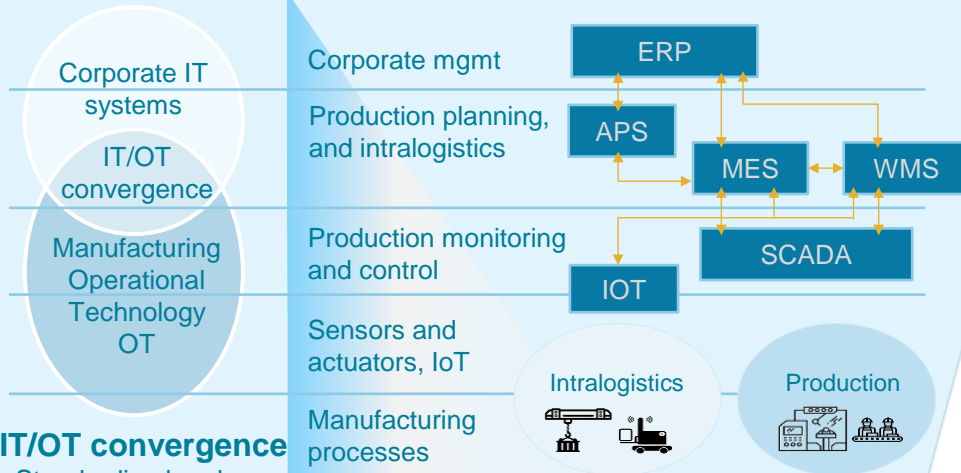


IDS Reference architecture model

IoT-Edge-Cloud continuum:

- Federated and distributed data and compute architecture enables advanced timely analytic services and applications

Industrial automation

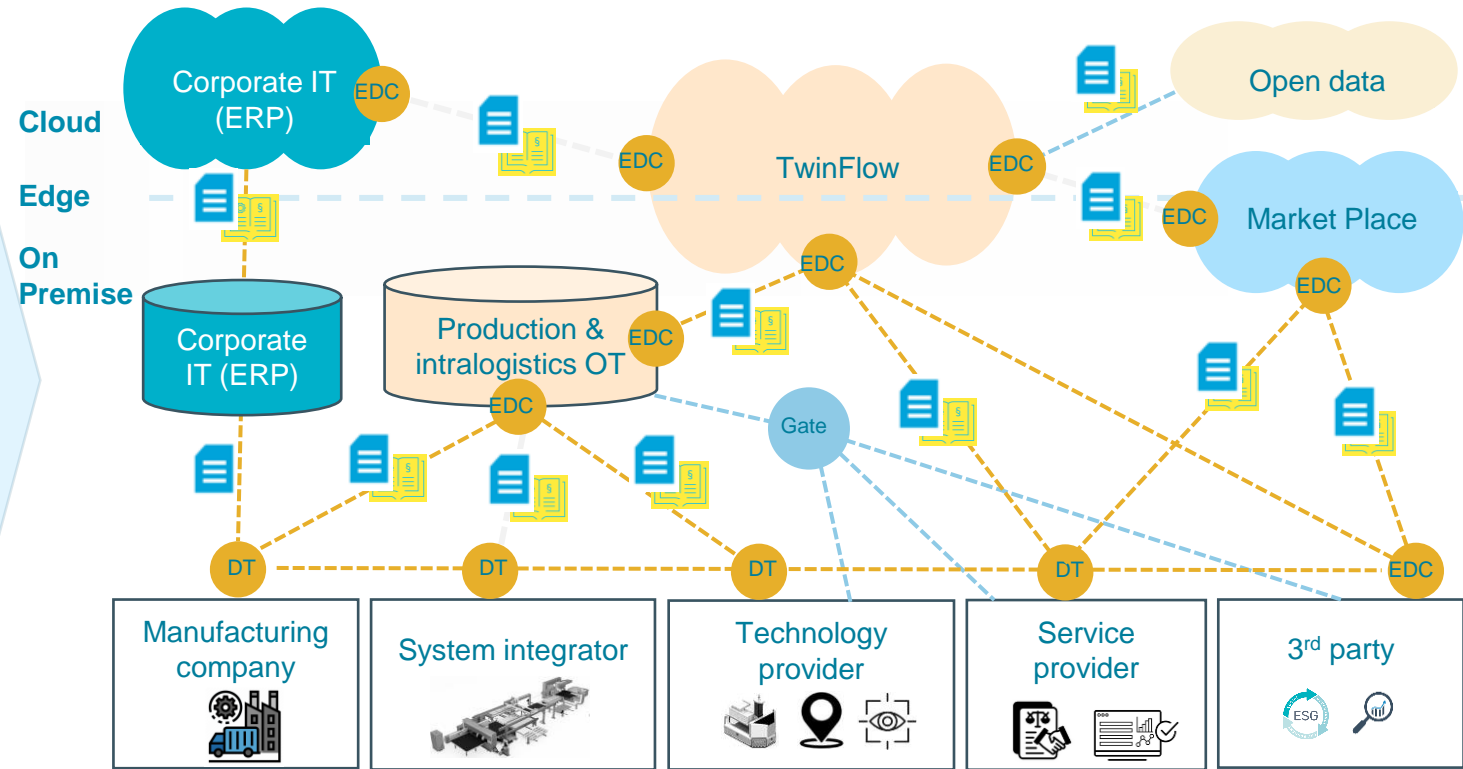


IT/OT convergence

- Standardized and scalable integration of corporate IT and manufacturing Operations Technologies OT

ISA-95: relation and responsibilities between enterprise systems, production operational systems and automation:

TwinFlow Concept



- EDC TwinFlow connector (EDC compliant)
- TwinFlow governance (IDSA compliant)
- Digital Twin documentation
- TwinFlow – external communication

TwinFlow Partners and Roles

Ecosystem facilitation

KONECRANES
Lifting Businesses™
Ecosystem orchestration, **industrial PoCs**. New business opportunities

A" Testbeds: Industrial Internet Campu AIIC & Factory of Future
Aalto-yliopisto

Tampere University Federated architecture over Edge-Cloud Continuum, distributed data

Production-Intralogistics integrator



Industrial PoC: Manufacturing asset interoperability and compatibility for enhanced material flow



Industrial PoC: Enhanced interoperability, situation awareness and advanced manufacturing operations management



Industrial PoC: Data compatibility in manufacturing ecosystems



Production-Intralogistics implementation



Industrial PoC and testbed merging production, intralogistics and IT



Logistics solution provider: testbeds for **industrial PoCs**.



UWB positioning based added value offering enhancing manufacturing operations mgmt



Data ecosystems, data governance & rule books: data architecture, business and legal.



Machine vision & advanced analytics in asset tracking for enhanced situational awareness



Integration of engineering, manufacturing and intraplant logistics

TwinFlow Research Teams

A”
Aalto-yliopisto
Prof Kari Tanskanen: SCI, Industrial Engineering and Management, Logistics

A”
Aalto-yliopisto
Risto Ojala: ENG Autonomous Systems; Tracking & Tracing, Machine Vision & Identification

A”
Aalto-yliopisto
Jari Juhanko: TwinFlow PI: Mechatronics, Industrial Internet: Technology, Business, Legal & People

A”
Aalto-yliopisto
Ilkka Lakaniemi: BIZ, Fair Data Economy, Data Sharing Ecosystems

A”
Aalto-yliopisto
Prof. Esko Niemi: ENG Production Engineering; Production Planning & Control,

A”
Aalto-yliopisto
Udayanto Atmoyo: ELEC, Industrial Automation, Cyber Physical Systems

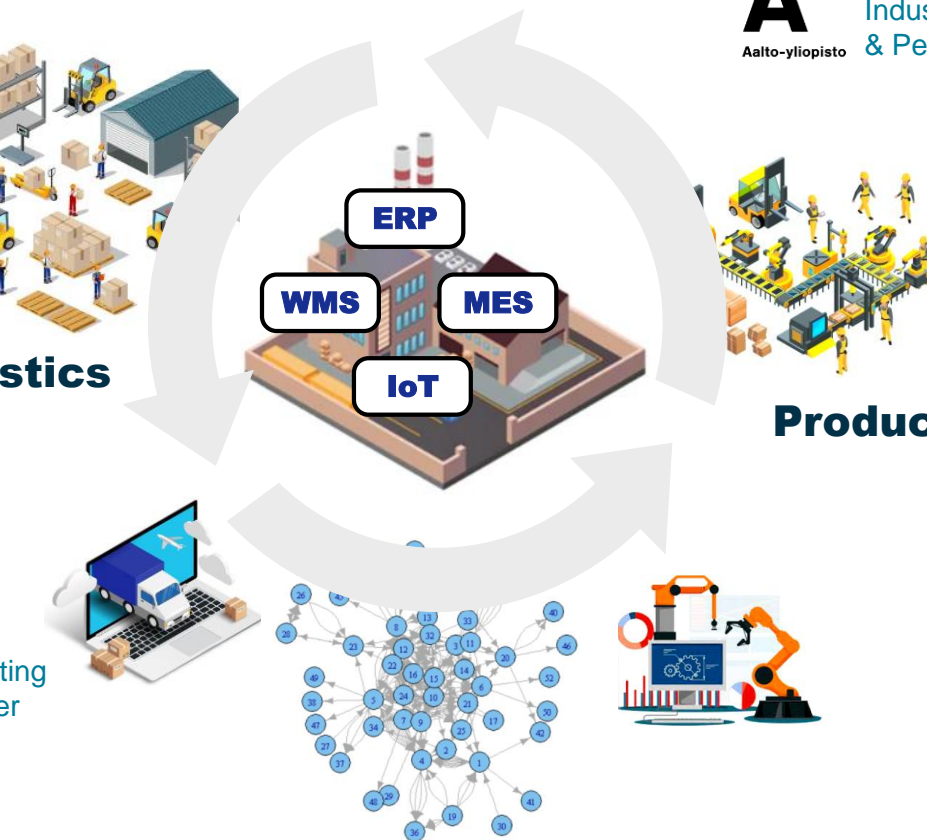
A”
Aalto-yliopisto
Riku Ala-Laurinaho: ENG Digital Industry, Semantic Digital Twins, Ontologies

 Tampere University
Prof. David Hästbacka: TAU, Computing Sciences; Federated Architecture over Edge-Cloud Continuum

A”
Aalto-yliopisto
Prof. Marko Turpeinen: SCI Computer Science: Data Sharing & Governance, IT&OT Interoperability

Intralogistics

Production



Research Goals

- We propose **standard architecture model**, common ontology and standards-compatible IT/OT integration platform for advanced analytics across management systems.
- We **integrate heterogeneous data** from IT/OT systems, added with identification, tracking, tracing, indoor positioning and machine vision systems for enhanced **situational awareness**.
- We build **demonstrators and showcases** together with industry, technology providers and service partners

Impact

- **Improved LEAN and OEE metrics:** Situation awareness enables factory level optimization and better decision making
- **New data driven business:** *Standard architecture model and legal framework* enable strategic partnerships – production-intralogistics operations as a service
- **Scalability:** Standard way of sharing data can be extended to upstream and downstream in the supply chain. Similarly, quality, maintenance, sustainability and energy could benefit from shared information and situational awareness



TwinFlow:

***Filling in a few of 1000 piece
digitalization puzzle***

Aurora Co-innovation

Forward'27 Webinar

21.2.2022

Project Manager Jukka Yrjänäinen et al, Tampere University

Aurora: Automated and Connected Machines

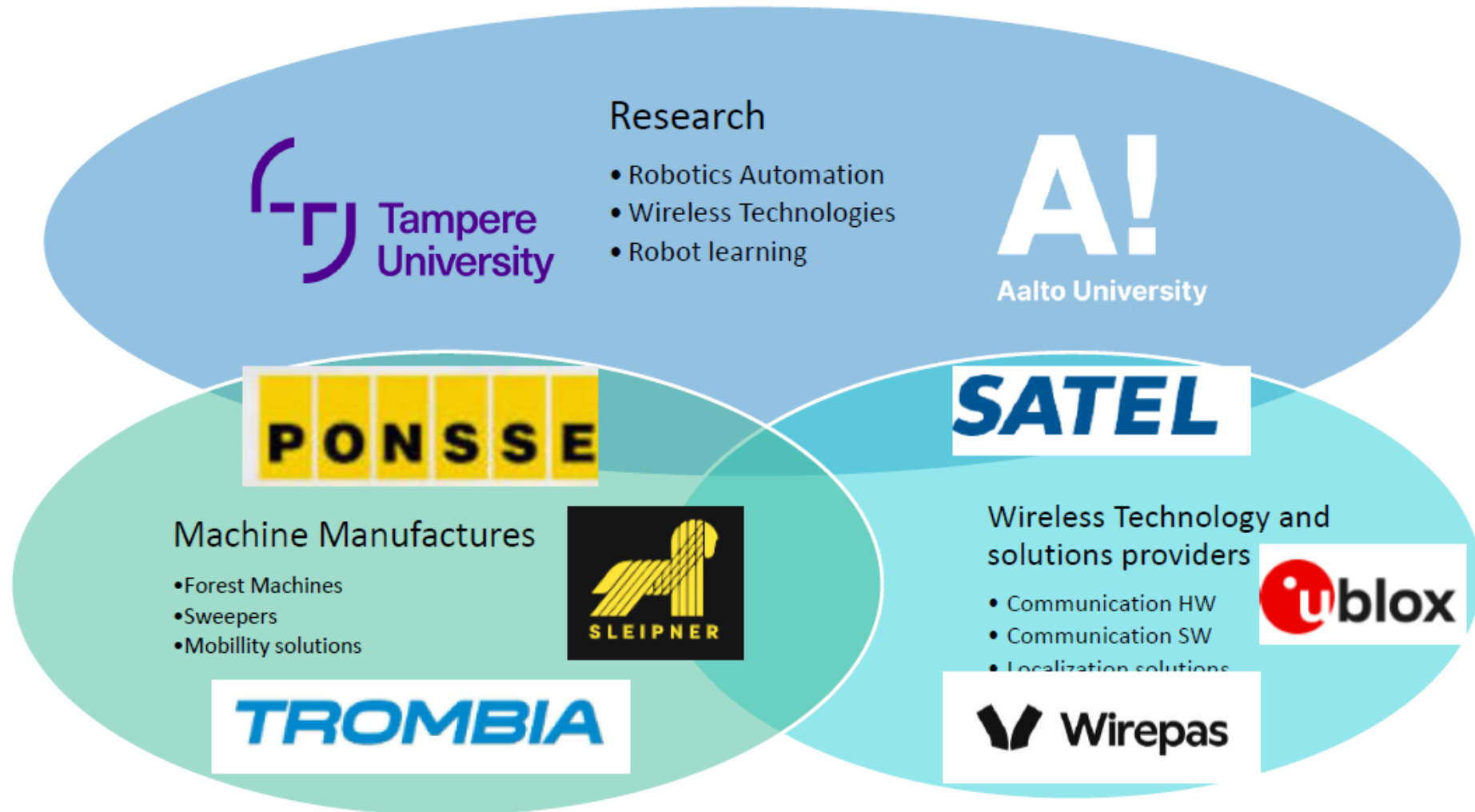
Project focuses on combining advanced
Wireless technologies and **Robotics**_{with AI} research in the

application field of

Heavy Working Machines

(Forest machines, Excavators, Street sweepers, Trucks, Forklifts, Mining Machines ... etc.)

Consortium Partners



Aurora public consortium in brief

Tampere University

- Robotics: Professor Reza Ghabcheloo (PI)
- Wireless: Professor Mikko Valkama

Aalto University

- Robot Learning: Professor Joni Pajarinen

Budget for the public research ~2 M€

Schedule Jan 2025 – Oct 2026

- Likely to be extended to spring 2027

Industry:

Ponsse (Veturi)

Sleipner

Trombia

Satel

Wirepas

u-blox

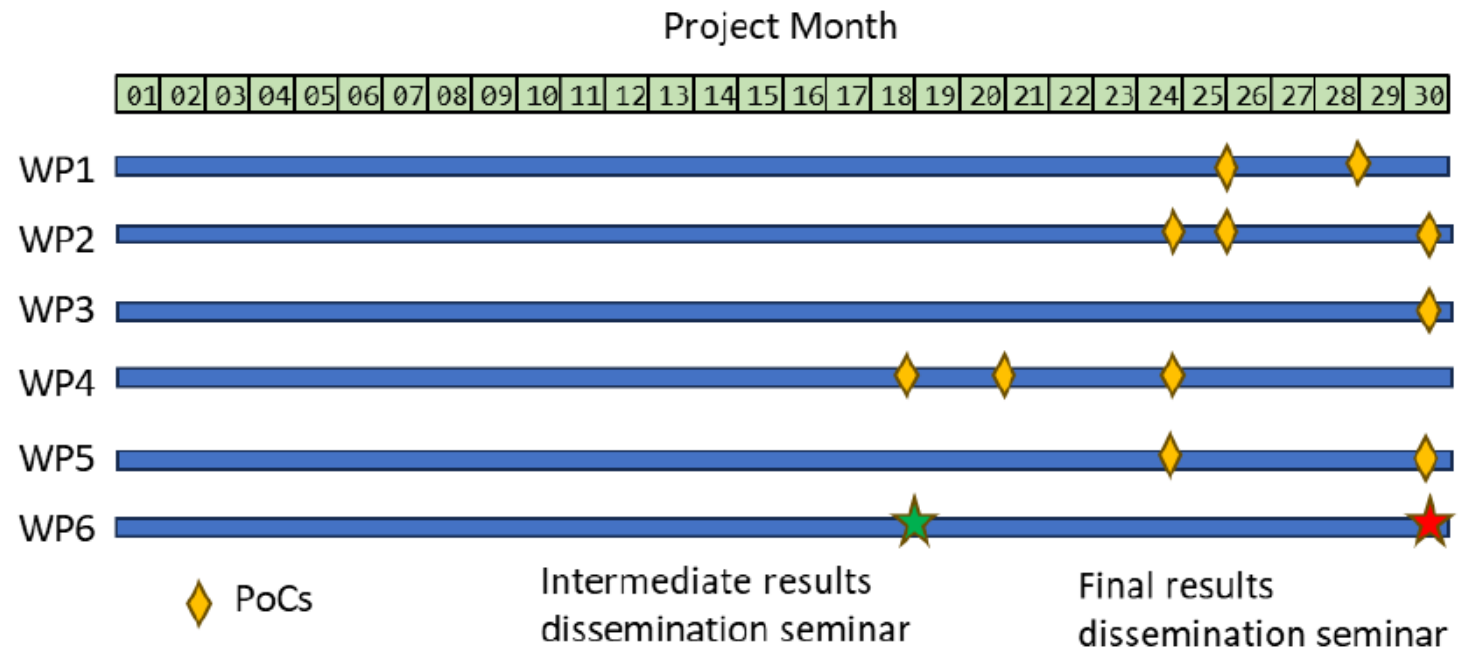
Project Schedule

Research project has started in the beginning of this year.

Company projects have been started earlier 24.5.2024.

Planned end of the project is Oct 2026, but due to delays in funding decision it is likely that project will be extended to spring 2027.

- Five technical Work Packages that produce different PoCs
- Two Larger seminars to disseminate the results.



Project results dissemination



Projects aims to create Proof-of-Concepts to demonstrate technology and research results.



Public, open for industry, results dissemination seminars will be arranged.



Results will be disseminated in the form of scientific publications, research reports and thesis works.



Work Packages

WP1: Multi technology radio communication

- Multiple state of the art connectivity technologies enabling **communication inside and between the machines**, and **machine to the cloud**.
- This WP focuses on the research of **highly scalable and reliable low-latency radio access solutions** for intelligent machines.

WP2: Robust state estimation and distributed control over wireless network

- **Robust algorithms for state estimation** based on information received over wireless network (e.g. IMUs, encoders) and local information (e.g. motion models).
- State estimation uncertainty and reliability is also calculated. Predicted uncertainty measures are used to optimize communication for energy consumption.

WP3: Advanced learning for high performance and fault tolerant control

- Investigation of **data driven techniques to learn machine motion models** and develop **reinforcement learning based controllers** for machine control for the desired objectives, such as high-performance path following.
- State uncertainty estimates provided by WP2 are used to robustly and safely control the machine to maintain a guaranteed certain control objectives such as path following error bounds.

WP4: Radio based ranging, positioning, and sensing.

- Research target is **radio-based and radio + other sensors -based situational awareness** for future intelligent machines with focus on the challenging **6DoF tracking in real-time**, as well as sensing and mapping of the machine environment.
- Object detection using **4D MIMO Radar** to measure relative pose of different part of machine or that of between the machine and other objects in the line of sight

WP5: Shared human-machine control

- We research how a **human can safely and smoothly control machine with limited or challenging wireless connectivity**. We will study how operator joy-stick commands (Boom control case) or commands through visual interfaces (Driving control case) can be used to define the control objectives and modify the behaviour of the local autonomous/safety controllers running on the edge.

Example PoCs, but not limited to these ...

Fault tolerant control of the machine (driving or manipulation) based on wirelessly transmitted sensor data.

Boom state (position, velocity) estimation based on combining RF measurements and other sensor data.

Remote shared control (teleoperation) over the wireless channel.



Thank You!

Q & A

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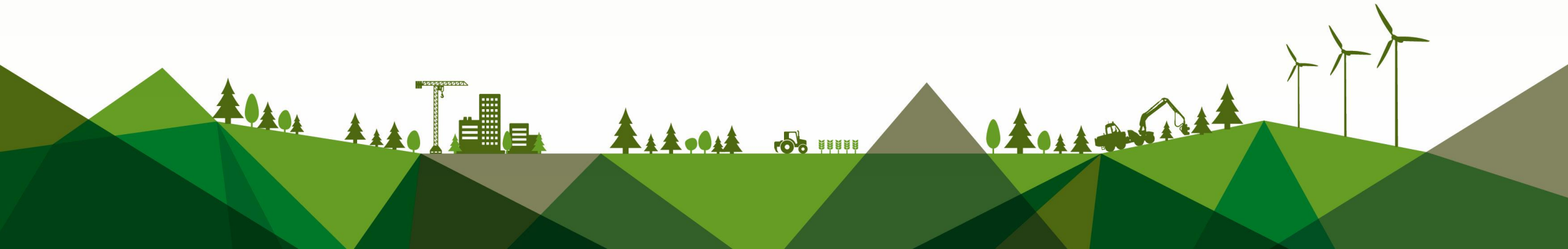
**KIITOS!
THANK YOU!**

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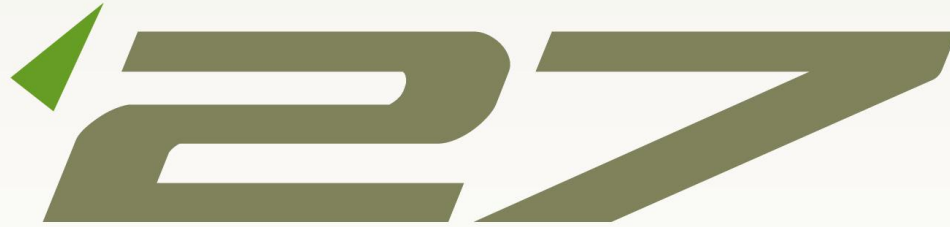
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